

## RECAP

$$\dot{x} = -x - 4y$$

$$\dot{y} = -2y - 5x$$

▷ IGNORANDO OS TERMOS EM VERMELHO  
TODAS SOLUÇÕES VÃO A ZERO

▷ SISTEMA TEM SOLUÇÕES QUE DIVERGEM.

## RECAP

$$\dot{x} = -x - 4y$$

$$\dot{y} = -2y - 5x$$



$$\begin{aligned} x(t) &= e^{3t} \\ y(t) &= -e^{3t} \end{aligned} \Rightarrow \vec{x} = e^{3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Como vetores

$$\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix} \Rightarrow \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} -1 & -4 \\ -5 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\dot{\vec{x}} = A \vec{x}$$

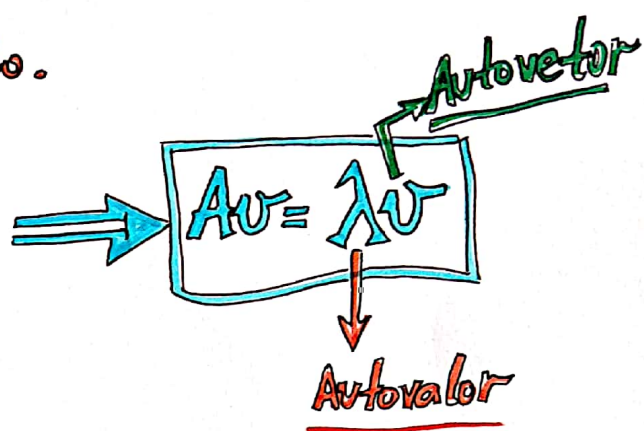
$$A = \begin{pmatrix} -1 & -4 \\ -5 & -2 \end{pmatrix}$$

- Autovetores de A ?

- Autovalores de A ?

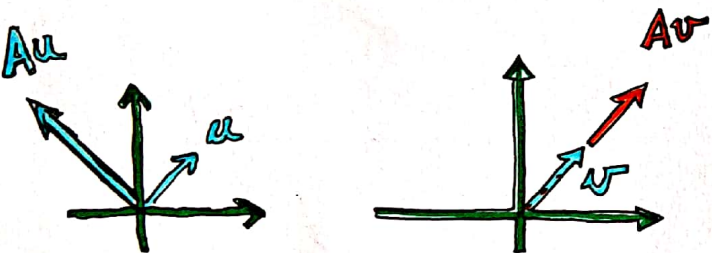
Existe algum vetor  $\vec{u}$  nulo.  
que a matriz  
A  $\vec{u}$  roda?

⇒ FUNDAMENTAL  
ME PREOCUPO COM POUCOS  
NÚMEROS



## AUTOVETOR

$$A\vec{u} = \lambda\vec{u} ; \vec{u} \neq 0$$



$$A\vec{u} = \lambda\vec{u}$$

$A\vec{u}$  é paralelo a  $\vec{u}$ .

## AUTOVALOR

$$A\vec{u} - \lambda\vec{u} = 0 \Rightarrow (A - \lambda I)\vec{u} = 0$$

▷ RECAP:  $B\vec{u} = 0$  SE  $B^{-1}$  EXISTE  $\Rightarrow \vec{u} = 0$

$$\det A \neq 0 \Leftrightarrow \exists A^{-1}$$

PORTANTO  $\vec{u} \neq 0$  TEMOS  $\det(A - \lambda I) = 0$ .

$$P_A(\lambda) = \det(A - \lambda I)$$

Polinômio característico

## 8 SOLUÇÃO GERAL

DADO  $\vec{x} \in \mathbb{R}^n$  &  $A \in \mathbb{R}^{n \times n}$

Considere o P.V.I.

$$\frac{d\vec{x}}{dt} = A\vec{x}, \quad \vec{x}(0) = x_0$$

Então a solução é ÚNICA DADA

$$\vec{x}(t) = e^{At} \vec{x}_0$$

ONDE

$$\vec{x}(t) = \left[ \mathbb{1} + At + \frac{1}{2}A^2t^2 + \frac{1}{3!}A^3t^3 + \dots \right] \vec{x}_0$$

EXPONENCIAL  
DE  
MATRIZ

Prova:

$$\begin{aligned} (\vec{x}(t))' &= \left( \mathbb{1} + At + \frac{1}{2}A^2t^2 + \dots \right)' \vec{x}_0 \\ &= \left( A + A^2t + A^3 \frac{t^2}{2} + \dots \right) \vec{x}_0 \\ &= \underbrace{A \left( \mathbb{1} + At + \frac{A^2t^2}{2} + \dots \right)}_{e^{At}} \vec{x}_0 \\ &= A\vec{x}(t) \end{aligned}$$

PELO TEOREMA DE PICARD A  
SOLUÇÃO É ÚNICA

NOTA: SE  $A = \begin{pmatrix} a & b \\ 0 & c \end{pmatrix}$

$$e^A \neq \begin{pmatrix} e^a & e^b \\ e^0 & e^c \end{pmatrix}$$

Thm:  $A \in \mathbb{R}^{n \times n}$

$$A\vec{u} = \lambda\vec{u} \iff e^{At}\vec{u} = e^{\lambda t}\vec{u}$$

Prova:  $\Rightarrow$

$$e^{At}\vec{u} = \left(1 + A + \frac{1}{2}A^2 + \frac{1}{3!}A^3 + \dots\right)\vec{u}$$

NOTE  $A^2\vec{u} = \lambda^2\vec{u}$  &  $A^n\vec{u} = \lambda^n\vec{u}$

$$e^{At}\vec{u} = \left(\vec{u} + A\vec{u} + \frac{1}{2}A^2\vec{u} + \dots\right)$$

$$= \left(\vec{u} + \lambda\vec{u} + \frac{1}{2}\lambda^2\vec{u} + \dots\right)$$

$$= \left(1 + \lambda + \frac{1}{2}\lambda^2 + \frac{1}{3!}\lambda^3 + \dots\right)\vec{u}$$

$$= e^{\lambda t}\vec{u}$$

CASO  $2 \times 2$   $A \in \mathbb{R}^{2 \times 2}$

$$A\vec{u} = \lambda\vec{u}$$

$$A\vec{v} = \beta\vec{v}$$

$$\lambda \neq \beta$$

Prop:  $\Gamma = \{\vec{u}, \vec{v}\}$  é base de  $\mathbb{R}^2$

PORTANTO  $\forall \vec{x}_0 \in \mathbb{R}^2$

$$\vec{x}_0 = c_1\vec{u} + c_2\vec{v}$$

$$\vec{x}(t) = e^{At}\vec{x}_0 = e^{At}(c_1\vec{u} + c_2\vec{v})$$

$$= c_1 e^{At}\vec{u} + c_2 e^{At}\vec{v}$$

$$\vec{x}(t) = c_1 e^{\lambda t}\vec{u} + c_2 e^{\beta t}\vec{v}$$

$$\underline{\text{Ej}} \quad A = \begin{pmatrix} -1 & -4 \\ -5 & -2 \end{pmatrix}$$

Pol CARAC  $p(\lambda) = \det(A - \lambda I)$

$$p(\lambda) = \begin{vmatrix} -1-\lambda & -4 \\ -5 & -2-\lambda \end{vmatrix} = \lambda^2 + 3\lambda - 18$$

$$p(\lambda) = 0 \Rightarrow \begin{aligned} \lambda_1 &= -6 \\ \lambda_2 &= 3 \end{aligned}$$

AUTOVALORES  $\lambda_1 = -6$

AUTOVECTOR  $v_1 = \begin{pmatrix} a \\ b \end{pmatrix}$

$$[A - (-6)I]v_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 5 & -4 \\ -5 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} -5a + 4b &= 0 \\ b &= \frac{5}{4}a \end{aligned}$$

$$v_1 = \begin{pmatrix} 1 \\ 5/4 \end{pmatrix}$$

AUTOVALOR  $\lambda_2 = 3$

AUTOVECTOR  $v_2 = \begin{pmatrix} a \\ b \end{pmatrix}$

$$\begin{pmatrix} -4 & -4 \\ -5 & -5 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow 4a + 4b = 0$$

$$v_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

NOTE:  $\Gamma = \left\{ \begin{pmatrix} 1 \\ 5/4 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$  E' BASE DE  $\mathbb{R}^2$

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} \in \mathbb{R}^2 \quad \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$A \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = c_1 A \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} + c_2 A \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$= -6c_1 \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} + 3c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\begin{cases} \dot{\vec{x}} = \underbrace{\begin{pmatrix} -1 & -4 \\ -5 & -2 \end{pmatrix}}_A \vec{x} \\ \vec{x}(0) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \end{cases}$$

Como  $A \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} = -6 \begin{pmatrix} 1 \\ 5/4 \end{pmatrix}$

&  $A \begin{pmatrix} -1 \\ -1 \end{pmatrix} = 3 \begin{pmatrix} -1 \\ -1 \end{pmatrix}$

TEMOS

$$\vec{x}(t) = c_1 e^{-6t} \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} + c_2 e^{3t} \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

$$\vec{x}(0) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 5/4 \end{pmatrix} + c_2 \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

$$\Rightarrow c_1 = 0 \text{ \& } c_2 = 1.$$

EDO 2º ORDEM ESCALAR COMO SISTEMA

$$x: \mathbb{R} \rightarrow \mathbb{R}$$

EQ CARA

$$x'' + ax' + bx = 0 \Rightarrow \lambda^2 + a\lambda + b = 0$$

1º PASSO  $y = x' \Rightarrow x'' = y'$

$$\therefore y' = -a \underbrace{x'}_y - bx$$

2º PASSO

$$x' = y$$

$$y' = -ay - bx$$

$$; \vec{X} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\dot{\vec{X}} = \underbrace{\begin{pmatrix} 0 & 1 \\ -b & -a \end{pmatrix}}_A \vec{X}$$

$$\begin{aligned} p_A(\lambda) &= \det(A - \lambda I) = \begin{vmatrix} -\lambda & 1 \\ -b & -a-\lambda \end{vmatrix} \\ &= \lambda^2 + a\lambda + b \end{aligned}$$